6ES7510-1DK03-0AB0

Data sheet



SIMATIC DP, CPU 1510SP-1 PN for ET 200SP, central processing unit with work memory 200 KB for program and 1 MB for data, 1st interface: PROFINET IRT with 3-port switch, 6 ns bit performance, SIMATIC Memory Card required, BusAdapter required for port 1 and 2

General information			
Product type designation	CPU 1510SP-1 PN		
HW functional status	FS04		
Firmware version	V4.0		
FW update possible	Yes		
Product function			
● I&M data	Yes; I&M0 to I&M3		
 Module swapping during operation (hot swapping) 	Yes; Multi-hot swapping		
 Isochronous mode 	Yes; only with PROFINET; with minimum OB 6x cycle of 500 µs		
SysLog	Yes		
Engineering with			
STEP 7 TIA Portal configurable/integrated from version	V20 (FW V4.0) / V18 (FW V3.0) or higher; configurable with older TIA Portal versions as 6ES7510-1DJ01-0AB0		
Configuration control			
via dataset	Yes		
Control elements			
Mode selector switch	1		
Supply voltage			
Rated value (DC)	24 V		
permissible range, lower limit (DC)	19.2 V		
permissible range, upper limit (DC)	28.8 V		
Reverse polarity protection	Yes		
Mains buffering			
 Mains/voltage failure stored energy time 	10 ms		
Input current			
Current consumption (rated value)	0.48 A		
Current consumption, max.	0.7 A		
Inrush current, max.	1.34 A; Rated value		
l²t	0.3 A ² ·s		
Power			
Infeed power to the backplane bus	8.05 W		
Power loss			
Power loss, typ.	3.5 W		
Memory			
Number of slots for SIMATIC memory card	1		
SIMATIC memory card required	Yes		
Work memory			
• integrated (for program)	200 kbyte		
• integrated (for data)	1 Mbyte		
Load memory			

 Plug-in (SIMATIC Memory Card), max. 	32 Gbyte
Backup	
maintenance-free	Yes
CPU processing times	
for bit operations, typ.	6 ns
for word operations, typ.	7 ns
for fixed point arithmetic, typ.	9 ns
for floating point arithmetic, typ.	37 ns
CPU-blocks	
Number of elements (total)	4 000; Blocks (OB, FB, FC, DB) and UDTs
DB	
Number range	1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max.	1 Mbyte; For DBs with absolute addressing, the max. size is 64 KB
FB	1 Mbyte, 1 of bbs with absolute addressing, the max. Size is 64 Nb
Number range	0 65 535
• Size, max.	200 kbyte
FC	
Number range	0 65 535
• Size, max.	200 kbyte
ОВ	
• Size, max.	200 kbyte
Number of free cycle OBs	100
 Number of time alarm OBs 	20
 Number of delay alarm OBs 	20
Number of cyclic interrupt OBs	20; With minimum OB 3x cycle of 250 µs
Number of process alarm OBs	50
Number of DPV1 alarm OBs	3
Number of isochronous mode OBs	1
Number of technology synchronous alarm OBs	2
Number of startup OBs	100
Number of asynchronous error OBs	4
Number of synchronous error OBs	2
Number of diagnostic alarm OBs	1
Nesting depth	
per priority class	24
Counters, timers and their retentivity	
S7 counter	
Number	2 048
Retentivity	2010
— adjustable	Yes
IEC counter	100
Number	Any (only limited by the main memory)
Retentivity	, ()
— adjustable	Yes
S7 times	
Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
Number	Any (only limited by the main memory)
Retentivity	, , , , , , , , , , , , , , , , , , , ,
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	256 kbyte; in total; available retentive memory for bit memories, timers, counters, DBs, and technology data (axes): 216 KB
Flag	
• Size, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	
Retentivity adjustable	Yes

Retentivity preset	No
Retentivity preset Local data	INO
	64 khyto: may 16 KP par block
per priority class, max. Address area	64 kbyte; max. 16 KB per block
	0.040. many growth and formativities (submandivities
Number of IO modules	2 048; max. number of modules / submodules
I/O address area	
• Inputs	32 kbyte; All inputs are in the process image
• Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	A.V
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
per CM/CP	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	
Number of subprocess images, max.	32
Address space per module	
Address space per module, max.	288 byte; For input and output data respectively
Address space per station	
Address space per station, max.	2 560 byte; for central inputs and outputs; depending on configuration; 2 048 bytes for ET 200SP modules + 512 bytes for ET 200AL modules
Hardware configuration	
Number of distributed IO systems	32; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
• Via CM	1
Number of IO Controllers	
• integrated	1
• Via CM	0
Rack	
Modules per rack, max.	82; CPU + 64 modules + server module (mounting width max. 1 m) + 16 ET 200AL modules
 Quantity of operable ET 200SP modules, max. 	64
 Quantity of operable ET 200AL modules, max. 	16
 Number of lines, max. 	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
Time of day	
Clock	
• Type	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	. ,
Number	16
Clock synchronization	
• supported	Yes
• to DP, master	Yes; Via CM DP module
• on DP, device	Yes; Via CM DP module
• in AS, master	Yes
• in AS, master	Yes
₹ III AO, UEVICE	100
on Ethernet via NTD	Vac
on Ethernet via NTP Interfaces	Yes
Interfaces	
Interfaces Number of PROFINET interfaces	1
Number of PROFIBUS interfaces Number of PROFIBUS interfaces	1 1; Via CM DP module
Interfaces Number of PROFINET interfaces Number of PROFIBUS interfaces Optical interface	1
Interfaces Number of PROFINET interfaces Number of PROFIBUS interfaces Optical interface 1. Interface	1 1; Via CM DP module
Interfaces Number of PROFINET interfaces Number of PROFIBUS interfaces Optical interface 1. Interface Interface types	1 1; Via CM DP module Yes; Via SIMATIC BusAdapter
Interfaces Number of PROFINET interfaces Number of PROFIBUS interfaces Optical interface 1. Interface Interface types • RJ 45 (Ethernet)	1 1; Via CM DP module Yes; Via SIMATIC BusAdapter Yes; X1 P3; opt. X1 P1 and X1 P2 via BusAdapter BA 2x RJ45
Interfaces Number of PROFINET interfaces Number of PROFIBUS interfaces Optical interface 1. Interface Interface types	1 1; Via CM DP module Yes; Via SIMATIC BusAdapter

BusAdapter (PROFINET)	Yes; compatible BusAdapters: BA 2x RJ45, BA 2x M12, BA 2x FC, BA 2x LC, BA LC/RJ45, BA LC/FC, BA 2x SCRJ, BA SCRJ/RJ45, BA SCRJ/FC	
Protocols		
IP protocol	Yes; IPv4	
PROFINET IO Controller	Yes	
PROFINET IO Device	Yes	
SIMATIC communication	Yes	
Open IE communication	Yes; Optionally also encrypted	
Web server	Yes	
Media redundancy	Yes	
PROFINET IO Controller		
Services		
— Isochronous mode	Yes	
Direct data exchange	Yes; Requirement: IRT and isochronous mode (MRPD optional)	
— IRT	Yes	
— PROFlenergy	Yes; per user program	
— Prioritized startup	Yes; Max. 32 PROFINET devices	
— Number of connectable IO Devices, max.	128; In total, up to 512 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET	
 Of which IO devices with IRT, max. 	64	
 Number of connectable IO Devices for RT, max. 	128	
— of which in line, max.	128	
 Number of IO Devices that can be simultaneously activated/deactivated, max. 	8; in total across all interfaces	
 Number of IO Devices per tool, max. 	8	
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data	
— PROFINET Security Class	1	
Update time for IRT		
— for send cycle of 250 μs	$250~\mu s$ to 4 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 500 μs of the isochronous OB is decisive	
— for send cycle of 500 μs	500 μs to 8 ms	
— for send cycle of 1 ms	1 ms to 16 ms	
— for send cycle of 2 ms	2 ms to 32 ms	
— for send cycle of 4 ms	4 ms to 64 ms	
— With IRT and parameterization of "odd" send cycles	Update time = set "odd" send clock (any multiple of 125 μ s: 375 μ s, 625 μ s 3 875 μ s)	
Update time for RT		
— for send cycle of 250 μs	250 μs to 128 ms	
— for send cycle of 500 μs	500 μs to 256 ms	
— for send cycle of 1 ms	1 ms to 512 ms	
— for send cycle of 2 ms	2 ms to 512 ms	
— for send cycle of 4 ms	4 ms to 512 ms	
PROFINET IO Device		
Services		
— Isochronous mode	No	
— IRT	Yes	
— PROFlenergy	Yes; per user program	
— Shared device	Yes	
 Number of IO Controllers with shared device, max. 	4	
 activation/deactivation of I-devices 	Yes; per user program	
 Asset management record 	Yes; per user program	
— PROFINET Security Class	SNMP Configuration and DCP Read Only	
2. Interface		
Interface types		
• RS 485	Yes; Via CM DP module	
Number of ports	1	
Protocols		
PROFIBUS DP master	Yes	
PROFIBUS DP device	Yes	
SIMATIC communication	Yes	

 Number of connections, max. 	48; Of which 4 each reserved for ES and HMI
 max. number of DP devices 	125; In total, up to 512 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
Candaga	PROFIDUS 01 PROFINE I
Services	Al-
— Equidistance	No
Isochronous mode	No
— activation/deactivation of DP devices	Yes
Interface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
Autonegotiation	Yes
Autocrossing	Yes
Industrial Ethernet status LED	Yes
RS 485	40.40.47
Transmission rate, max.	12 Mbit/s
Protocols	
PROFIsafe	No
Number of connections	
 Number of connections, max. 	128; via integrated interfaces of the CPU and connected CPs / CMs
 Number of connections reserved for ES/HMI/web 	10
 Number of connections via integrated interfaces 	88
 Number of connections per CP/CM 	32
Number of S7 routing paths	16
Redundancy mode	
H-Sync forwarding	Yes
Media redundancy	
Media redundancy	Yes; only via BusAdapter
— MRP	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client
MPD interconnection curported	Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
MRP interconnection, supported MRPD	Yes; Requirement: IRT
— Switchover time on line break, typ.	200 ms; For MRP, bumpless for MRPD
Number of stations in the ring, max.	50
SIMATIC communication	30
PG/OP communication	Yes; encryption with TLS V1.3 pre-selected
• S7 routing	Yes
Data record routing	Yes
S7 communication, as server	Yes
S7 communication, as server S7 communication, as client	Yes
User data per job, max.	See online help (S7 communication, user data size)
Open IE communication	See Offiline help (S7 Communication, user data size)
TCP/IP	Yes
— Data length, max.	64 kbyte
— several passive connections per port, supported	Yes
ISO-on-TCP (RFC1006) Data length, max	Yes
— Data length, max.● UDP	64 kbyte
	Yes 2 khyte: 1 472 hytes for LIDP broadcast
— Data length, max.— UDP multicast	2 kbyte; 1 472 bytes for UDP broadcast
	Yes; max. 78 multicast circuits
• DHCP	Yes
DNS SNMP	Yes Yes
• SNMP • DCP	Yes
• DCP • LLDP	Yes
Encryption Web server.	Yes; Optional
Web server	Voc. Standard and upor pages
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
• web API	50
— Number of sessions, max.	50
 number of simultaneous HTTP calls, max. 	4

— HTTP request body, max.	131 072 byte	
OPC UA		
Runtime license required	Yes; "Small" license required	
OPC UA Client	Yes; Data Access (registered Read/Write), Method Call	
 Application authentication 	Yes	
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256	
 User authentication 	"anonymous" or by user name & password	
 Number of connections, max. 	4	
 Number of nodes of the client interfaces, recommended max. 	1 000	
 Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_ReadList/OPC_I max. 	300	
 Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max. 	20	
 Number of elements for one call of OPC_UA_MethodGetHandleList, max. 	100	
 Number of simultaneous calls of the client instructions for session management, per connection, max. 	1	
 Number of simultaneous calls of the client instructions for data access, per connection, max. 	5	
 Number of registerable nodes, max. 	5 000	
 Number of registerable method calls of OPC_UA_MethodCall, max. 	100	
— Number of inputs/outputs when calling OPC_UA_MethodCall, max.	20	
OPC UA Server	Yes; data access (read, write, subscribe), method call, alarms & condition (A&C), custom address space, role-based access control	
 Application authentication 	Yes	
— Security policies	available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256, Aes128Sha256RsaOaep, Aes256Sha256RsaPss	
User authentication	"anonymous" or by user name & password	
 — GDS support (certificate management) 	Yes	
— Number of sessions, max.	32	
Number of accessible variables, max.	50 000	
Number of registerable nodes, max.	10 000	
Number of subscriptions per session, max. Sampling interval, min.	50 100 ms	
— Sampling interval, min.		
— Publishing interval, min.— Number of server methods, max.	200 ms	
,	20; max. 20 concurrently running jobs each for asynchronous instructions OPC_UA_ServerMethodPre and OPC_UA_ServerMethodPost	
Number of inputs/outputs per server method, max.	4 000 for 4 a compling interval and 4 a conditions	
— Number of monitored items, recommended max.— Number of server interfaces, max.	4 000; for 1 s sampling interval and 1 s send interval 10 of each "Server interfaces" / "Companion specification" type and 20 of the	
 Number of nodes for user-defined server interfaces, max. 	type "Reference namespace" 15 000	
Alarms and Conditions	Yes	
Number of program alarms	100	
Number of alarms for system diagnostics	50	
Further protocols		
MODBUS	Yes; MODBUS TCP	
S7 message functions		
Number of login stations for message functions, max.	32	
number of subscriptions, max.	250	
number of tags/attributes for subscriptions, max.	2 000	
Program alarms	Yes	
Number of configurable program messages, max.	5 000; Program messages are generated by the "Program_Alarm" block, ProDiag or GRAPH	
Number of loadable program messages in RUN, max.	5 000	
Number of simultaneously active program alarms		
 Number of program alarms 	600	
 Number of alarms for system diagnostics 	100	
 Number of alarms for motion technology objects 	160	

Test commissioning functions			
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 5 engineering systems		
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)		
Single step	Yes		
Number of breakpoints	8		
Profiling	Yes		
Status/control			
Status/control variable	Yes		
Variables			
Number of variables, max.	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters		
of which status variables, max.	200: per job		
of which control variables, max.	200; per job 200; per job		
Forcing	200, μει job		
Forcing	Yes		
Forcing, variables	Peripheral inputs/outputs		
Number of variables, max.	200		
Diagnostic buffer	200		
-	Yes		
Number of entries may	1 000		
Number of entries, max. of which powerful proof	500		
— of which powerfail-proof	000		
Traces	4		
Number of configurable Traces Memory size partrage, may	4 F12 khyta		
Memory size per trace, max. Intervente/diagnostics/status information.	512 kbyte		
Interrupts/diagnostics/status information			
Diagnostics indication LED			
• RUN/STOP LED	Yes		
• ERROR LED	Yes		
MAINT LED	Yes		
Monitoring of the supply voltage (PWR-LED)	Yes		
 Connection display LINK TX/RX 	Yes		
· •			
Supported technology objects			
	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool		
Supported technology objects Motion Control	program; selection guide via the TIA Selection Tool		
Supported technology objects			
Supported technology objects Motion Control • Number of available Motion Control resources for	program; selection guide via the TIA Selection Tool		
Supported technology objects Motion Control Number of available Motion Control resources for technology objects	program; selection guide via the TIA Selection Tool		
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources	program; selection guide via the TIA Selection Tool 1 120		
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis	program; selection guide via the TIA Selection Tool 1 120 40		
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis	program; selection guide via the TIA Selection Tool 1 120 40 80		
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis	program; selection guide via the TIA Selection Tool 1 120 40 80 160		
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80		
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value)	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Temp Counting and measuring	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp Counting and measuring High-speed counter Standards, approvals, certificates	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Step PID-Temp Counting and measuring High-speed counter Standards, approvals, certificates Ecological footprint	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter Standards, approvals, certificates Ecological footprint environmental product declaration	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_Astep PID_Temp Counting and measuring High-speed counter Standards, approvals, certificates Ecological footprint environmental product declaration Global warming potential, (total) [CO2 eq] global warming potential, (during production) [CO2	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes Yes		
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per external encoder per output cam per cam track per probe Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value) Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter Standards, approvals, certificates Ecological footprint environmental product declaration Global warming potential, (total) [CO2 eq]	program; selection guide via the TIA Selection Tool 1 120 40 80 160 80 20 160 40 11 14 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature Yes Yes 83.2 kg		

eq]	0.040 lv		
 — global warming potential, (after end of life cycle) [CO2 eq] 	-0.949 kg		
product functions / security / header			
PROFINET Security Class	1		
signed firmware update	Yes		
Secure Boot	Yes		
safely removing data	Yes		
Ambient conditions			
Ambient temperature during operation			
 horizontal installation, min. 	-30 °C; No condensation		
 horizontal installation, max. 	60 °C		
 vertical installation, min. 	-30 °C; No condensation		
vertical installation, max.	50 °C		
Altitude during operation relating to sea level			
Installation altitude above sea level, max.	5 000 m; Restrictions for installa	ation altitudes > 2 000 m,	see manual
configuration / header			
configuration / programming / header			
Programming language			
— LAD	Yes		
— FBD	Yes		
— STL	Yes		
— SCL	Yes		
— CFC	Yes		
— GRAPH	Yes		
Know-how protection	Voo		
User program protection/password protectionCopy protection	Yes Yes		
Block protection	Yes		
Access protection	165		
protection protection of confidential configuration data	Yes		
Protection level: Write protection	Yes		
Protection level: Read/write protection	Yes Yes		
Protection level: Write protection for Failsafe	Yes No		
Protection level: Complete protection	No Yes		
User administration	Yes; device-wide and centralize	ed	
Number of users	100		
Number of groups	100		
Number of roles	50		
programming / cycle time monitoring / header			
• lower limit	adjustable minimum cycle time		
• upper limit	adjustable maximum cycle time		
Dimensions			
Width	100 mm		
Height	117 mm		
Depth	75 mm		
Weights			
Weight, approx.	265 g		
Classifications			
		Version	Classification
	eClass	14	27-24-26-07
	eClass	12	27-24-26-07
	eClass	9.1	27-24-26-07
	eClass	9	27-24-26-07
	eClass	8	27-24-26-07
	eClass	7.1	27-24-26-07
	eClass	6	27-24-26-07
	ETIM	9	EC001603
	ETIM	8	EC001603
	L I IIVI		_0001000

ETIM	7	EC001603
IDEA	4	3565
UNSPSC	15	32-15-17-05

Approvals / Certificates

General Product Approval





Miscellaneous

Manufacturer Declaration



Miscellaneous

General Product Approval

For use in hazardous locations









<u>FM</u>

CCC-Ex

For use in hazardous locations

Maritime application





Miscellaneous

CCC-Ex





Maritime application





PROFINET

NK / Nippon Kaiji Ky-<u>okai</u>





CCS (China Classification Society)

other

Environment





last modified:

12/8/2024

