# **SIEMENS**

## **Data sheet**

## 6ES7512-1DM03-0AB0



SIMATIC DP, CPU 1512SP-1 PN for ET 200SP, central processing unit with work memory 400 KB for program and 2 MB for data, 1st interface: PROFINET IRT with 3-port switch, 6 ns bit performance, SIMATIC Memory Card required, BusAdapter required for port 1 and 2

Figure similar

Conoral information		
General information	ODUL 45400D 4 DN	
Product type designation	CPU 1512SP-1 PN	
HW functional status	FS04	
Firmware version	V4.0	
FW update possible	Yes	
Product function		
I&M data	Yes; I&M0 to I&M3	
<ul> <li>Module swapping during operation (hot swapping)</li> </ul>	Yes; Multi-hot swapping	
<ul> <li>Isochronous mode</li> </ul>	Yes; only with PROFINET; with minimum OB 6x cycle of 500 μs	
SysLog	Yes	
Engineering with		
STEP 7 TIA Portal configurable/integrated from version	V20 (FW V4.0) / V18 (FW V3.0) or higher; configurable with older TIA Portal versions as 6ES7 512-1DK01-0AB0	
Configuration control		
via dataset	Yes	
Control elements		
Mode selector switch	1	
Supply voltage		
Rated value (DC)	24 V	
permissible range, lower limit (DC)	19.2 V	
permissible range, upper limit (DC)	28.8 V	
Reverse polarity protection	Yes	
Mains buffering		
<ul> <li>Mains/voltage failure stored energy time</li> </ul>	10 ms	
Input current		
Current consumption (rated value)	0.48 A	
Current consumption, max.	0.7 A	
Inrush current, max.	1.34 A; Rated value	
l²t	0.3 A <sup>2</sup> ·s	
Power		
Infeed power to the backplane bus	8.05 W	
Power loss		
Power loss, typ.	3.5 W	
Memory		
Number of slots for SIMATIC memory card	1	
SIMATIC memory card required	Yes	
Work memory		
integrated (for program)	400 kbyte	
• integrated (for data)	2 Mbyte	

Lord warrange	
Load memory  • Plug in (SIMATIC Memory Card) may	32 Chuta
Plug-in (SIMATIC Memory Card), max.	32 Gbyte
Backup	Yes
maintenance-free  CDL pressessing times	res
CPU processing times	0 ==
for bit operations, typ.	6 ns
for word operations, typ.	7 ns
for fixed point arithmetic, typ.	9 ns
for floating point arithmetic, typ.	37 ns
CPU-blocks	4.000 Planta (OR ER EQ DR) and URT-
Number of elements (total)  DB	4 000; Blocks (OB, FB, FC, DB) and UDTs
	1 60 000; subdivided into: number range that can be used by the user; 1
Number range	1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max.	1 Mbyte; For DBs with absolute addressing, the max. size is 64 KB
FB	
Number range	0 65 535
• Size, max.	400 kbyte
FC	
Number range	0 65 535
• Size, max.	400 kbyte
OB	
• Size, max.	400 kbyte
Number of free cycle OBs	100
<ul> <li>Number of time alarm OBs</li> </ul>	20
Number of delay alarm OBs	20
<ul> <li>Number of cyclic interrupt OBs</li> </ul>	20; With minimum OB 3x cycle of 250 μs
<ul> <li>Number of process alarm OBs</li> </ul>	50
<ul> <li>Number of DPV1 alarm OBs</li> </ul>	3
<ul> <li>Number of isochronous mode OBs</li> </ul>	1
<ul> <li>Number of technology synchronous alarm OBs</li> </ul>	2
<ul> <li>Number of startup OBs</li> </ul>	100
<ul> <li>Number of asynchronous error OBs</li> </ul>	4
<ul> <li>Number of synchronous error OBs</li> </ul>	2
<ul> <li>Number of diagnostic alarm OBs</li> </ul>	1
Nesting depth	
<ul> <li>per priority class</li> </ul>	24
Counters, timers and their retentivity	
S7 counter	
Number	2 048
Retentivity	
— adjustable	Yes
IEC counter	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
S7 times	
Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	256 kbyte; in total; available retentive memory for bit memories, timers,
Flor	counters, DBs, and technology data (axes): 216 KB
Flag	40 libida
Size, max.  Number of cleak marrories.	16 kbyte
Number of clock memories  Date blacks	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	

a Detentivity adjustable	Yes
Retentivity adjustable     Retentivity property	No
Retentivity preset  Local data	INO
per priority class, max.	64 kbyte; max. 16 KB per block
Address area	04 kbyte, max. 10 kb per block
Number of IO modules	2 048; max. number of modules / submodules
I/O address area	2 046, max. number of modules / submodules
	32 kbyte; All inputs are in the process image
<ul><li>Inputs</li><li>Outputs</li></ul>	32 kbyte; All inputs are in the process image
per integrated IO subsystem	32 kbyte, All outputs are in the process image
	8 kbyte
<ul><li>— Inputs (volume)</li><li>— Outputs (volume)</li></ul>	8 kbyte
per CM/CP	o kuyte
	9 khyto
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	22
Number of subprocess images, max.  Address appearance mediula.	32
Address space per module	288 byte: For input and output data respectively.
Address space per module, max.  Address space per station.	288 byte; For input and output data respectively
Address space per station	2.560 bute: for central inpute and autoute: depending an configuration, 2.040
<ul> <li>Address space per station, max.</li> </ul>	2 560 byte; for central inputs and outputs; depending on configuration; 2 048 bytes for ET 200SP modules + 512 bytes for ET 200AL modules
Hardware configuration	
Number of distributed IO systems	32; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
• Via CM	1
Number of IO Controllers	
integrated	1
• Via CM	0
Rack	
Modules per rack, max.	82; CPU + 64 modules + server module (mounting width max. 1 m) + 16 ET 200AL modules
<ul> <li>Quantity of operable ET 200SP modules, max.</li> </ul>	64
<ul> <li>Quantity of operable ET 200AL modules, max.</li> </ul>	16
Number of lines, max.	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
Time of day	
Clock	
• Type	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	
Number	16
Clock synchronization	
• supported	Yes
• to DP, master	Yes; Via CM DP module
• on DP, device	Yes; Via CM DP module
• in AS, master	Yes
• in AS, device	Yes
• on Ethernet via NTP	Yes
Interfaces	
Number of PROFINET interfaces	1
Number of PROFIBUS interfaces	1; Via CM DP module
Optical interface	Yes; Via SIMATIC BusAdapter
1. Interface	
Interface types	
• RJ 45 (Ethernet)	Yes; X1 P3; opt. X1 P1 and X1 P2 via BusAdapter BA 2x RJ45
Number of ports	3; 1. integr. + 2. via BusAdapter
•	•

integrated switch	Yes		
BusAdapter (PROFINET)	Yes; compatible BusAdapters: BA 2x RJ45, BA 2x M12, BA 2x FC, BA 2x LC, BA LC/RJ45, BA LC/FC, BA 2x SCRJ, BA SCRJ/RJ45, BA SCRJ/FC		
Protocols	Break is, Break s, Break solve, Break is is, Break in S		
IP protocol	Yes; IPv4		
PROFINET IO Controller	Yes		
PROFINET IO Device	Yes		
SIMATIC communication	Yes		
Open IE communication	Yes; Optionally also encrypted		
Web server	Yes		
Media redundancy	Yes		
PROFINET IO Controller			
Services			
— Isochronous mode	Yes		
Direct data exchange	Yes; Requirement: IRT and isochronous mode (MRPD optional)		
— IRT	Yes		
— PROFlenergy	Yes; per user program		
Prioritized startup	Yes; Max. 32 PROFINET devices		
Number of connectable IO Devices, max.	128; In total, up to 512 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET		
<ul> <li>Of which IO devices with IRT, max.</li> </ul>	64		
Number of connectable IO Devices for RT, max.	128		
— of which in line, max.	128		
<ul> <li>Number of IO Devices that can be simultaneously activated/deactivated, max.</li> </ul>	8; in total across all interfaces		
Number of IO Devices per tool, max.	8		
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data		
— PROFINET Security Class	1		
Update time for IRT			
— for send cycle of 250 μs	$250~\mu s$ to 4 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 500 $\mu s$ of the isochronous OB is decisive		
— for send cycle of 500 μs	500 μs to 8 ms		
— for send cycle of 1 ms	1 ms to 16 ms		
— for send cycle of 2 ms	2 ms to 32 ms		
— for send cycle of 4 ms	4 ms to 64 ms		
— With IRT and parameterization of "odd" send cycles	Update time = set "odd" send clock (any multiple of 125 $\mu s:375~\mu s,625~\mu s3875~\mu s)$		
Update time for RT			
— for send cycle of 250 μs	250 µs to 128 ms		
— for send cycle of 500 μs	500 μs to 256 ms		
— for send cycle of 1 ms	1 ms to 512 ms		
— for send cycle of 2 ms	2 ms to 512 ms		
— for send cycle of 4 ms	4 ms to 512 ms		
PROFINET IO Device			
Services			
— Isochronous mode	No		
— IRT	Yes		
— PROFlenergy	Yes; per user program		
— Shared device	Yes		
<ul> <li>Number of IO Controllers with shared device, max.</li> </ul>	4		
<ul> <li>activation/deactivation of I-devices</li> </ul>	Yes; per user program		
<ul> <li>Asset management record</li> </ul>	Yes; per user program		
— PROFINET Security Class	SNMP Configuration and DCP Read Only		
2. Interface			
Interface types			
• RS 485	Yes; Via CM DP module		
Number of ports	1		
Protocols			
PROFIBUS DP master	Yes		
PROFIBUS DP device	Yes		

PROFIBUS DP master	
Number of connections, max.	48; Of which 4 each reserved for ES and HMI
• max. number of DP devices	125; In total, up to 512 distributed I/O devices can be connected via AS-i,
	PROFIBUS or PROFINET
Services	
— Equidistance	No
— Isochronous mode	No
activation/deactivation of DP devices	Yes
nterface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
<ul> <li>Autonegotiation</li> </ul>	Yes
• Autocrossing	Yes
Industrial Ethernet status LED	Yes
RS 485	
Transmission rate, max.	12 Mbit/s
Protocols	
PROFIsafe	No
Number of connections	
Number of connections, max.	128; via integrated interfaces of the CPU and connected CPs / CMs
Number of connections reserved for ES/HMI/web	10
Number of connections via integrated interfaces	88
Number of connections per CP/CM	32
Number of S7 routing paths	16
Redundancy mode	
H-Sync forwarding	Yes
Media redundancy	
— Media redundancy	Yes; only via BusAdapter
— MRP	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client
- MRP interconnection, supported	Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
— MRPD	Yes; Requirement: IRT
Switchover time on line break, typ.	200 ms; For MRP, bumpless for MRPD
Number of stations in the ring, max.	50
SIMATIC communication	
PG/OP communication	Yes; encryption with TLS V1.3 pre-selected
• S7 routing	Yes
Data record routing	Yes
S7 communication, as server	Yes
S7 communication, as client	Yes
User data per job, max.	See online help (S7 communication, user data size)
Open IE communication	2001 and one (20 annual model of a data of 20)
• TCP/IP	Yes
— Data length, max.	64 kbyte
several passive connections per port, supported	Yes
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	2 kbyte; 1 472 bytes for UDP broadcast
— UDP multicast	Yes; max. 78 multicast circuits
• DHCP	Yes
• DNS	Yes
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
• Encryption	Yes; Optional
Web server	
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
• web API	

— number of simultaneous HTTP calls, max.	4	
— HTTP request body, max.	131 072 byte	
OPC UA		
Runtime license required	Yes; "Small" license required	
OPC UA Client	Yes; Data Access (registered Read/Write), Method Call	
<ul> <li>Application authentication</li> </ul>	Yes	
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256	
<ul><li>User authentication</li></ul>	"anonymous" or by user name & password	
<ul><li>Number of connections, max.</li></ul>	4	
<ul> <li>Number of nodes of the client interfaces, recommended max.</li> </ul>	1 000	
<ul> <li>Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_ReadList/OPC_I max.</li> </ul>	300	
<ul> <li>Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max.</li> </ul>	20	
<ul> <li>Number of elements for one call of OPC_UA_MethodGetHandleList, max.</li> </ul>	100	
<ul> <li>Number of simultaneous calls of the client instructions for session management, per connection, max.</li> </ul>	1	
<ul> <li>Number of simultaneous calls of the client instructions for data access, per connection, max.</li> </ul>	5	
<ul> <li>Number of registerable nodes, max.</li> </ul>	5 000	
<ul> <li>Number of registerable method calls of OPC_UA_MethodCall, max.</li> </ul>	100	
<ul> <li>Number of inputs/outputs when calling OPC_UA_MethodCall, max.</li> </ul>	20	
OPC UA Server	Yes; data access (read, write, subscribe), method call, alarms & condition (A&C), custom address space, role-based access control	
— Application authentication	Yes	
— Security policies	available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256, Aes128Sha256RsaOaep, Aes256Sha256RsaPss	
— User authentication	"anonymous" or by user name & password	
GDS support (certificate management)	Yes	
Number of sessions, max.	32	
Number of accessible variables, max.	50 000 10 000	
<ul><li>— Number of registerable nodes, max.</li><li>— Number of subscriptions per session, max.</li></ul>	50	
Sampling interval, min.	100 ms	
— Samping interval, min.  — Publishing interval, min.	200 ms	
— Publishing interval, min.      — Number of server methods, max.	20; max. 20 concurrently running jobs each for asynchronous instructions OPC_UA_ServerMethodPre and OPC_UA_ServerMethodPost	
<ul> <li>Number of inputs/outputs per server method, max.</li> </ul>	20	
Number of monitored items, recommended max.	4 000; for 1 s sampling interval and 1 s send interval	
— Number of server interfaces, max.	10 of each "Server interfaces" / "Companion specification" type and 20 of the type "Reference namespace"	
<ul> <li>Number of nodes for user-defined server interfaces, max.</li> </ul>	15 000	
Alarms and Conditions	Yes	
— Number of program alarms	100	
Number of alarms for system diagnostics	50	
Further protocols		
MODBUS	Yes; MODBUS TCP	
7 message functions		
Number of login stations for message functions, max.	32	
number of subscriptions, max.	250	
number of tags/attributes for subscriptions, max.	2 000	
Program alarms  Number of configurable program messages, max.	Yes  5 000; Program messages are generated by the "Program_Alarm" block, Propling or CPAPH	
Number of loadable program messages in RUN, max.	ProDiag or GRAPH 5 000	
Number of simultaneously active program alarms		
Number of program alarms	600	
<ul> <li>Number of alarms for system diagnostics</li> </ul>	100	

	160	
Number of alarms for motion technology objects  Test commissioning functions		
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 5 engineering systems	
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)	
Single step	Yes	
Number of breakpoints	8	
Profiling	Yes	
Status/control		
Status/control variable	Yes	
Variables	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters	
Number of variables, max.		
— of which status variables, max.	200; per job	
— of which control variables, max.	200; per job	
Forcing	200, por 100	
• Forcing	Yes	
Forcing, variables	Peripheral inputs/outputs	
Number of variables, max.	200	
Diagnostic buffer		
• present	Yes	
Number of entries, max.	1 000	
— of which powerfail-proof	500	
Traces		
Number of configurable Traces	4	
Memory size per trace, max.	512 kbyte	
Interrupts/diagnostics/status information		
Diagnostics indication LED		
RUN/STOP LED	Yes	
• ERROR LED	Yes	
MAINT LED	Yes	
<ul> <li>Monitoring of the supply voltage (PWR-LED)</li> </ul>	Yes	
<ul> <li>Connection display LINK TX/RX</li> </ul>	Yes	
Supported technology objects		
Motion Control	Yes; Note: The number of technology objects affects the cycle time of the PLC	
	program: colection guide via the TIA Selection Tool	
	program; selection guide via the TIA Selection Tool	
Number of available Motion Control resources for technology objects	1 120	
technology objects		
technology objects • Required Motion Control resources	1 120	
technology objects  ● Required Motion Control resources  — per speed-controlled axis		
technology objects • Required Motion Control resources	1 120	
technology objects  • Required Motion Control resources  — per speed-controlled axis  — per positioning axis	1 120 40 80	
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis	1 120 40 80 160	
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder	1 120 40 80 160 80	
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam	1 120 40 80 160 80 20	
technology objects  • Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track	1 120  40 80 160 80 20 160	
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle	1 120  40 80 160 80 20 160	
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)	1 120  40 80 160 80 20 160 40	
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle	1 120  40  80  160  80  20  160  40	
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)	1 120  40 80 160 80 20 160 40	
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller	1 120  40 80 160 80 20 160 40 11	
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact	1 120  40 80 160 80 20 160 40 11 14  Yes; Universal PID controller with integrated optimization	
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_SStep	1 120  40 80 160 80 20 160 40 11 14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves	
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_Step  PID-Temp	1 120  40 80 160 80 20 160 40 11 14  Yes; Universal PID controller with integrated optimization	
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_3Step  PID-Temp  Counting and measuring	1 120  40 80 160 80 20 160 40  11  14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature	
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_Step  PID-Temp  Counting and measuring  High-speed counter	1 120  40 80 160 80 20 160 40 11 14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves	
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_3Step  PID-Temp  Counting and measuring  High-speed counter  Standards, approvals, certificates	1 120  40 80 160 80 20 160 40  11  14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature	
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_Step  PID-Temp  Counting and measuring  High-speed counter  Standards, approvals, certificates  Ecological footprint	1 120  40 80 160 80 20 160 40  11 14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Yes	
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_Step  PID-Temp  Counting and measuring  High-speed counter  Standards, approvals, certificates  Ecological footprint  environmental product declaration	1 120  40 80 160 80 20 160 40  11  14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature	
technology objects  Required Motion Control resources  — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe  Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact PID_Step PID-Temp  Counting and measuring High-speed counter  Standards, approvals, certificates  Ecological footprint environmental product declaration Global warming potential	1 120  40 80 160 80 20 160 40  11 14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Yes  Yes	
technology objects  Required Motion Control resources  — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe  Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact PID_Step PID-Temp  Counting and measuring High-speed counter  Standards, approvals, certificates  Ecological footprint  environmental product declaration	1 120  40 80 160 80 20 160 40  11 14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Yes	

— global warming potential, (during operation) [CO2	61 9 kg			
eq]	61.8 kg			
— global warming potential, (after end of life cycle) [CO2 eq]	-0.949 kg			
product functions / security / header				
PROFINET Security Class	1			
signed firmware update	Yes			
Secure Boot	Yes			
safely removing data	Yes			
Ambient conditions				
Ambient temperature during operation				
<ul> <li>horizontal installation, min.</li> </ul>	-30 °C; No condensation			
<ul> <li>horizontal installation, max.</li> </ul>	60 °C			
<ul> <li>vertical installation, min.</li> </ul>	-30 °C; No condensation			
vertical installation, max.	50 °C			
Altitude during operation relating to sea level				
Installation altitude above sea level, max.	5 000 m; Restrictions for installa	ation altitudes > 2 000 m,	see manual	
configuration / header				
configuration / programming / header				
Programming language				
— LAD	Yes			
— FBD	Yes			
— STL	Yes			
— SCL	Yes			
— CFC	Yes			
— GRAPH	Yes			
Know-how protection				
<ul> <li>User program protection/password protection</li> </ul>	Yes	Yes		
<ul> <li>Copy protection</li> </ul>	Yes			
Block protection	Yes			
Access protection				
<ul> <li>protection of confidential configuration data</li> </ul>	Yes			
<ul> <li>Protection level: Write protection</li> </ul>	Yes			
<ul> <li>Protection level: Read/write protection</li> </ul>	Yes			
<ul> <li>Protection level: Write protection for Failsafe</li> </ul>	No			
<ul> <li>Protection level: Complete protection</li> </ul>	Yes			
<ul> <li>User administration</li> </ul>	Yes; device-wide and centralized			
<ul> <li>Number of users</li> </ul>	100			
<ul> <li>Number of groups</li> </ul>	100			
Number of roles	50			
programming / cycle time monitoring / header				
<ul><li>lower limit</li></ul>	adjustable minimum cycle time			
• upper limit	adjustable maximum cycle time			
Dimensions				
Width	100 mm			
Height	117 mm			
Depth	75 mm			
Weights				
Weight, approx.	265 g			
Classifications				
		Version	Classification	
	eClass	14	27-24-26-07	
	eClass	12	27-24-26-07	
	eClass	9.1	27-24-26-07	
	eClass	9	27-24-26-07	
	eClass	8	27-24-26-07	
	eClass	7.1	27-24-26-07	
	eClass	6	27-24-26-07	
	ETIM	9	EC001603	

ETIM	8	EC001603
ETIM	7	EC001603
IDEA	4	3565
UNSPSC	15	32-15-17-05

### Approvals / Certificates

#### **General Product Approval**

Manufacturer Declara-<u>tion</u>





**Miscellaneous** 



**Miscellaneous** 

## **General Product Approval**



<u>KC</u>



For use in hazardous locations

<u>FM</u>

CCC-Ex

#### For use in hazardous locations





**Miscellaneous** 

CCC-Ex



Marine / Shipping



## Marine / Shipping





**PROFINET** 

NK / Nippon Kaiji Ky-okai





CCS (China Classification Society)

other

Environment



Profibus



last modified:

12/8/2024

